## MASTERARBEIT

# Cooperation in human-dog dyads during <br> Leash walks: The influence of Human PERSONALITY AND THE INTENSITY OF CONTACT. 

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## 1 ZUSAMMENFASSUNG (GERMAN SUMMARY)

Das Ziel meiner Masterarbeit war es, herauszufinden ob und inwieweit die Bindung zu einer bestimmten Person, die Kontaktintensität und die Persönlichkeit einer Person das kooperative Verhalten von Mensch und Hund im Laufe von Leinenspaziergängen beeinflusst. Basis meiner Arbeit war die Diplomarbeit von Margit Auer (2009), welche die Kooperation zwischen Wolf und Mensch untersuchte, um festzustellen, welche Parameter diese Interaktion beeinflussen. Meine Studie fand am Wolf Science Center in Ernstbrunn, in Niederösterreich statt. Es nahmen insgesamt 18 Hunde und 28 Spaziergänger daran teil. Daraus resultierten 54 verschiedene dyadische Kombinationen. Um Informationen über die Wichtigkeit, der „sozialen Bindung" zwischen Mensch und Hund zu erhalten, wurden Spaziergänge von den 18 teilnehmenden Hunden zusammen mit dem Besitzer, einer bekannten Person für den Hund, die aber nicht der Besitzer war und einer fremden Person, die der Hund zuvor noch nie gesehen hat gefilmt. Während des 80 m langen Spaziergangs wurden die Zweierteams (Dyaden) gebeten, die Übungen „Sitz" und „Platz" zu absolvieren Das Verhalten von Hund und Mensch wurde anschließend vom Videoband kodiert. Farbige Holzpfeiler markierten den Anfang, das Ende und die Position der Übungen. Der Hund und sein Spaziergänger gingen zwei verschieden Routen, welche im Wildpark von Ernstbrunn positioniert waren. Ziel war es, dass jeder der Hunde mit jedem seiner Spaziergänger (Besitzer, Freund, Fremder), jede der zwei Routen zweimal bestreitet. Dafür waren zwei Treffen mit den Teilnehmern vorgesehen. Aus logistischen Gründen schafften es 6 der Hunde nur einmal zu kommen. Die Hunde waren von ein bis sechs Jahre alt und waren alle nicht kastriert. Jeder der Teilnehmer wurde außerdem gebeten, einen standardisierten Fragebogen, der die Persönlichkeit des Halters ermittelt (NEO-FFI Test entwickelt von Costa und McCrae (1989) und von Borkenau und Ostendorf (1993) ins Deutsche übersetzt), auszufüllen. Die Spaziergänge wurden gefilmt und mit Hilfe des Softwareprogramms THE OBSERVER Video Pro® (Version 5.0; Noldus) codiert. Die statistische Analyse beinhaltet Kruskal-Wallis-Tests und LMEs (linear mixed effort model).

Sowohl der Freund als auch die fremde Person zeigten ein weniger kooperatives Verhalten mit dem Hund als der Besitzer, der weniger oft eine gespannte Leine
initiierte. Auch war die Dauer in welcher die Leine lose fiel, länger für Besitzer, als für Freunde oder Fremde. Die Anzahl der Führungskonflikte war außerdem geringer in Spaziergängen mit dem Besitzer.
Außerdem beeinflussten das Geschlecht von Mensch und Hund, sowie die Persönlichkeit des Menschen, die soziale Interaktion innerhalb der Leinenspaziergang - Dyade. Zum Beispiel zeigten extravertierte und offene Spaziergänger eine geringere Anzahl an Führungskonflikten als Gewissenhafte (NEO-FFI Dimensionen). Hunde, mit extravertierten Spaziergängern initiierten weniger oft eine gespannte Leine. Im Gegensatz dazu, initiierten Hunde von neurotizistischen Partnern, sowie die Partner selbst öfters eine gespannte Leine. Neurotizistische und extravertierte Partner streichelten ihre Hunde öfter als gewissenhafte, verträgliche und offene Partner.

Unsere Ergebnisse können zu einem besseren Verständnis von Mensch-Hund Beziehungen beitragen. In diesem Sinn wäre ein systemischer Ansatz, also die Einbeziehung der sozialen Beziehung zwischen Mensch und Hund, sowie die Persönlichkeit beider Partner sicher hilfreich, um zukünftig das Training und die Arbeit mit Hunden zu verbessern.

## 2 Abstract

When dogs and humans act as social partners, several parameters like the personality of both, their attachment, age and gender will affect this relationship. Here I expanded on previous studies, using leash walking as an experimental paradigm and investigated the influence of these factors on the cooperative performance of human-dog dyads, in particular on the diploma thesis of Margit Auer (2009), who investigated the cooperation behaviour between human and wolves and the effect of personality and intensity of contact on the performance. The present study was performed at the Wolf Science Centre in Ernstbrunn, Lower Austria. Eighteen pet dogs participated with twenty-eight human leash walkers, resulting in .fifty-four different dyadic combinations. I recorded leash walks of a dog together with three different walkers: the owner of the dog, a familiar person who knew the dog well but was not the owner and a stranger, who never had seen the dog before. In addition, dyads were asked to do the exercises "sit" and "down" during the walk. Coloured wooden poles marked the sites where to start, to do the exercises, to turn and to end. The dyads walked two different, 80 m long tracks. Therefore each of the dog did at least one walk with each walker at each track. Dogs were between one and six years old and were all not castrated. Each of the walkers, were asked to fill in a NEO - FFI personality test .Walks were videotaped and behaviour was coded with THE OBSERVER Video Pro® (Version 5.0; Noldus). Data was analyzed with Kruskal-Wallis-Test and LMEs (linear mixed effort model). We indeed, found effects of attachment and the intensity of previous contact between walker and dog on leash walking performance. Owners were more cooperative with their own dog, than the friend-dog or the stranger-dog dyads were. In fact, the owner of the dog less often initiated a strained leash than the friend or the stranger and the time the leash was loose was longer for the owner than for the other two walkers. Owners also had less often leadership conflicts with their dogs and they were more successful in completing exercises with the dog than the other two walkers. In addition, owner gender and dog sex, as well as the personality of the walker affected the performance of human-dog dyads. For example, walkers high in extraversion and openness (NEO-FFI dimensions) showed relatively few leadership conflicts, whereas walkers high in
conscientiousness showed more of such conflicts. The higher a walker scored in extraversion, the less often the dog initiated a strained leash. In contrast, the higher a walker scored in neuroticism, the more often a dog, as well as the walker, initiated a strained leash. People high in neuroticism frequently touched their dogs, whereas walkers high in extraversion spoke less often with their dogs, than those low in this personality dimension, but also more often touched the dog during the walk.

In conclusion, our findings may contribute to a better understanding of human-dog relationships and may help trainers with a systemic approach, namely to focus on individual dyadic training, taking into regard parameters like the dog-owner relationships and their personalities.

Key Words: Human-dog interactions, cooperation, dyadic challenges, personality, gender interactions

## 3 INTRODUCTION

### 3.1 History of dog-human relationship and the personality of human

Wolves/dogs are known as the first animals which were living in close nonparasitic contact with humans for more then 16.000 years, with Far East (Savolainen et al., 2002; Pang et al., 2009) or Middle East origin (Pang et al., 2009; Gray and Wayne, 2010; Klütsch and de Caprona, 2010). Although the discussion, about when and how domestication started is still going on, it is clear that dogs were domesticated from wolves (Pang et al., 2009; Klütsch and de Caprona, 2010). Pang et al. (2009) analyzed entire mitochondrial genomes of 169 dogs and the results indicate that the domestic dog had it's origin in the southern China, less than 16.300 years ago from several hundred wolves. Schleidt and Shalter (2003) suggested that wolves may have followed humans, in order to benefit from their proximity. Ultimately, they shared a common ecology and history with humans for over 400.000 years (Clutton-Brock, 1995).

Over time, dogs became an increasingly important part of the human's live, be it as an assistant in herding and hunting (Naderi et al., 2001), as a social supporter (Allen, 1991; Friedmann, 1995; Kotrschal, 2009; Kotrschal \& Ortbauer, 2003; Wedl, 2009) or as a helper for disabled or blind people (Johnston, 1990), etc. Indeed, the relationships between dogs and humans, and the function of such relationships, may vary widely between cultures and dyads (Hart, 1995). Dogs can act as social supporters, as close friends, as companions for shared activities but also "just" as an animal which happens to live in the same household.

A number of studies revealed that dogs are good at communicating with humans. For example dogs seek contact to humans, if confronted with an unsolvable problem (Miklosi et al., 2003). Topál et al. (1997) showed that simple problem solving in the dog is strongly influenced by the relationship between the dog and the owner. Looking at each other and holding eye contact is an important cue when it comes to communication. Nagasawa (2009) measured urinary oxytocin concentrations of owners before and after interactions with their dogs. They found out that the gaze of dog's increase the urinary oxytocin levels of owners as an expression of attachment behaviour. Using the human as a communication partner and as a facility to perform tasks might be a consequence of the domestication
process (Hare et al., 2002). Some dog-human dyads perform in a highly coordinated way, according to complex tasks, whereas in others, dogs may not even react, when they were called by their owners. The question is which factors are mainly responsible for such relational and interactional differences. A study by Kotrschal et al. (2009) about the relationship between human personality and the performance of dog-human dyads, showed that dog owners who scored highly in neuroticism (according to Neo-FFI), considered their dogs as social supporters and they spent much time with them, but the dyads were less successful in solving a practical task than owners who scored high in extraversion (according to NeoFFI) and who considered their dogs as companions for shared activities.

### 3.2 Leash walks in order to test cooperation in human-dog dyads

Auer (2009) found, that the cooperative performance of socialized wolves is influenced by the familiarity to their cooperating partner. Topál et al. (1997) examined, whether dog - human relationships affect problem solving in dogs. They presumed that, poor performances of dogs in problem solving tasks are not due to their cognitive abilities but because of the inherited tendency of dogs to act socially dependently. In accordance with this hypothesis, the more socialized a dog (defined in terms of its fitting into the family structure and the attachment to a certain person), the more likely it is to behave like a member of a social bond. Behaviour problems in dogs arise from poor dog-human relationships rather than from poor obedience training (Voith et al., 1992). Further it is known, that the development of complex human-animal relationships will depend, at least in part, on the mode and intensity of attachment (Bowlby, 1999).

Cooperation can be defined as "individuals acting together to achieve a common goal" (Boesch and Boesch, 1989). Naderi et al. (2001) supposed that co-operative behaviour is an inherited trait in dogs and that it might be an important contributing factor in the development of successful guide dog performance. They studied cooperation behaviour in dogs, when leading a blind person and found out that the initiation of an action alternates continuously between the two partners. In fact, a leash walk is a complex cooperative action, because due to the leash, human and dogs are forced to work together and also the leash may be considered as an
instrument of communication. My study was pioneered by Margit Auer (2009), who did leash walks with the first four of the hand raised wolves at the Wolf Science Centre in Ernstbrunn, in order to investigate the cooperation between wolves and their hand raisers (Auer, 2009). A walk on the leash would also follow the three criteria of cooperation, defined by Naderi et al. (2001), based on definitions by Boesch and Boesch (1989) and Chalmeau and Gallo (1996):

- Congruence as a term to describe, whether individuals perform any behaviour similar or dissimilar. $\rightarrow$ Regarding the leash walk, our individuals perform actions similarly.
- Synchrony as a term to characterize the timing of the actions, if they are performed in parallel or sequentially. $\rightarrow$ Regarding the leash walks, the actions are performed in parallel.
- Spatial coordination to specify whether the individuals act together in close spatial proximity (homospheric) or if individuals depart and act independently (heterospheric). $\rightarrow$ The individuals of our study act together in spatial proximity, depending on the length of the leash (Auer, 2009).

Cooperative performance during a leash walk can be measured by a number of parameters, for example in the domain of communication. For example, we measured the amount of time and the frequency the walkers spoke, or did not speak with the dog. In order to get information about the distribution of leadership in the human - dog dyad, we observed which individual walked in front. A leadership conflict was noticed when the walk came to a stop due to incongruence in behaviour. The leash may be seen as a tool for the walker to make sure that the dog cannot escape, but also as a tool for enforcement and communication and also to provide some support and safety to the dog. A strained leash is caused by dyadic asymmetry between walker and dog, indicating a conflict. Other parameters considered, were the orientation of the head and the eyes of the dog as well as of the human, locomotion of both of the individuals and who initiated an interaction.

### 3.3 Hypotheses

My study featured 18 pet dogs, which did walks on the leash together with their owner, a familiar person and a total stranger to the dog. As in the case of the former study, I wanted to investigate the effect of the personality of humans and the intensity of contact on cooperation tasks. Further I examined, whether there are differences in the cooperation behaviour, according to the sex of the human and the dog.

Based on previous results (above), my main hypothesis is that there should be a relationship between the outcomes of a cooperative task, as in this case a walk on the leash and the amount of time the three walkers spent with the dog. This was used as an indicator for the intensity of contact. Therefore, we predict that the dog should behave more cooperatively during the walk on the leash, when it is with its owner than with just a known or even an unknown person.

Because personality of the owner was found to play an important role in influencing the relationship between human and dogs (O' Farrell, 1997; Kotrschal et al., 2009; Schöberl, 2009; Wedl and Kotrschal, 2009; Aliabadi, 2010; Wedl et al., 2010), my second hypothesis is that in parallel with the previous studies we expect an influence of human personality on the cooperation behaviour of human - dog dyads, with neuroticism and extraversion (Neo-FFI) being particularly important.

My third hypothesis focuses on the sex/gender differences in dogs as well as in humans. There are already data indicating that human-dog interactions are affected by human gender and dog sex (Wells \& Hepper, 1999). Women in general tend to be more emphatic and socially interested than men (Ray, 1982; Rost \& Hartmann, 1994; Prato-Previde et al., 2006). Some studies also suggest that women will talk more and will have more interactions with their dogs, while male owners will try to be fast at doing the required action and will not spent much time communicating with their dogs (reviewed in Hart, 1995; Prato-Previde et al. 2006). Therefore, we predict some differences in the interactions female and male owners may have with their male and female dogs and that the dogs may be sensitive to the walker's gender.

## 4 METHODS

This study was conducted at the Wolf Science Centre, positioned in the game park of Ernstbrunn (Lower Austria). The dogs used for this study, were 18 pet dogs, which are all living in households in the immediate vicinity and which took part voluntarily on this study together with their owners.

### 4.1 Subjects

This study is based on 18 dogs and 28 humans (twelve female and six male dogs as well as twenty-two female and six male walkers) who volunteered to participate in this experiment. The subjects were recruited by mail, by announcements in newspapers and on the internet and by postings, which I posted at locations near the game park, in Ernstbrunn and Steinbach. A data file with contact information's of owners and their dogs, used by the clever dog lab at the University of Vienna, served as basis for the search for possible volunteers for my study. All of the participated dogs were not castrated, but we imposed no restrictions regarding the breed or the sex of the animal. The dogs ranged from eleven month to five years of age (by the time they did the walks). We had eight border collies, two westland terriers, two huskies, one golden retriever, one miniature pinscher, one eurasier and three mongrels in our study (Table 1). The human participants ranged between 14 to 67 years of age.

| DOG | SEX | AGE <br> (in years) | BREED |
| :--- | :--- | :--- | :--- |
| Alika | Female | 1,5 | Mongrel |
| Becky | Female | 5 | Border collie |
| Chloe | Female | 0,11 | Westland terrier |
| Dakota | Female | 5 | Husky |
| Faye | Female | 1 | Border collie |
| Forest | Male | 5 | Husky |
| Hancoc | Male | 1 | Golden retriever |


| Idefix | Female | 1,5 | Westland terrier |
| :--- | :--- | :--- | :--- |
| Luke | Male | 6 | Boarder collie |
| Luna | Female | 5 | Eurasier |
| Mena | Female | 1 | Border collie |
| Merlin | Male | 1 | Boarder collie |
| Miley | Female | 2 | Boarder collie |
| Nanuk | Female | 5 | Mongrel |
| Shila | Female | 5 | Mongrel |
| Tiffany | Female | 2 | Miniature pinscher |
| Ultimo | Male | 1 | Boarder collie |
| Winnie | Male | 1 | Boarder collie |

Table 1: Participating dogs

Each of the dogs had to do a walk with his/her owner, a familiar person for the dog and a total stranger. Usually the familiar person for the dog was a friend of the family who spent a lot of time with the dog and who was known by the dog very well but who was not living in the same household as the dog. Just in one out of eighteen cases the familiar person was living in the same household as the dog (Table 2).

| Dogs | Familiar Person |
| :--- | :--- |
| Alika | Friend |
| Becky | Friend |
| Chloe | Gandfather |
| Dakota | Friend |
| Faye | Husband |
| Forest | Good sister |
| Hancoc | Friend |
| Idefix | Friend |
| Luke | Friend |
| Luna | Friend |
| Mena | Workmate |
| Merlin | Mother |


| Miley | Boyfriend |
| :--- | :--- |
| Nanuk | Sister |
| Shila | Sister |
| Tiffany | Friend |
| Ultimo | Friend |
| Winnie | Breeder |

Table 2 shows the relationship between the owner of the dog and the familiar person.

Four different subjects played the role of the stranger to the dog. Three of the four strangers were students of the Wolf Science Centre in Ernstbrunn and the fourth one was the owner of one of the participating dogs (Table 3). A strange person was defined as someone who never had seen the dog before. Some of the human participants walked with two or more different dogs, one time as owner of the dog, another time as friend for another dog. Only one of the participants walked with two different dogs as owner (Table 3).

| DOGS | OWNER (0) | FRIEND (F) | STRANGER (S) |
| :--- | :--- | :--- | :--- |
| Faye (f) | Of = Fw | Ff | Sf_1 |
| Winnie (w) | Ow | Fw = Of | Sf_1 |
| Ultimo (u) | Ou | Fu | Sf_1 |
| Mena (m) | Om | Fm | Sf_2 |
| Merlin (mer) | Omer | Fmer | Sf_2 |
| Alika (a) | Oa | Fa | Sf_4 = Oi = Oc =Fh |
| Hancoc (h) | Oh = Fi | Fh = Oi =Oc =Sa_4 | Sf_1 |
| Idefix (i) | Oi = Fh =Oc =Sa_4 | Fi = Oh | Sf_1 |
| Chloe (c) | Oc = Oi = Fh= Sa_4 | Fc | Sf_2 |
| Becky (b) | Ob = FI | Fb = Ow | Sf_2 |
| Luke (l) | Ol = Fb | FI =Ob | Sf_2 |
| Dakota (d) | Od = Flun | Fd = Olun | Sf_2 |
| Luna (lun) | Olun = Fd | Flun = Od | Sf_2 |
| Tiffany (t) | Ot | Ft | Sf_2 |
| Miley (mi) | Omi | Fmi | Sf_3 |
| Forest (fo) | Ofo | Ffo = Fn = Os | Sf_3 |


| Shila (s) | Os $=$ Ffo $=$ Fn | Fs $=$ On | Sf_3 |
| :--- | :--- | :--- | :--- |
| Nanuk (n) | On = Fs | Fn $=$ Ffo $=$ Os | Sf_3 |

Table 3: Dyads: 18 dogs; 28 different walkers: 7 walkers act as owner for one dog and as friend for another dog, 1 walker act onetime as Owner, and two times as friend; 1 walker act two times as owner, one time as friend and one time as stranger.

In order to test the cooperative behaviour of human-dog dyads, a standardized walk was designed. This standardized walk was located at the game park in Ernstbrunn at two different sites, to balance the potential influence of local conditions. Besides, all variables that might influence the walk performance were protocolled. This procedure was used already before, to test the cooperation behaviour of human-wolf dyads (Auer, 2009). For this, the hand raisers of the wolves did three walks with each wolf on three places. None of the animals should have more than one walk per day. A counterbalanced schedule made sure, that each animal got only one walk per day and that none of the animals walked the same track twice in a row. These measures counterbalanced habituation effects. In my study with pet dogs, conditions were a bit different, due to the fact that the owners do not live near the game park and therefore could not come so often. Each of the pet dogs was scheduled to do two walks on two different tracks with each of the three walkers (owner, familiar person and stranger). The owner of the dog, the friend and the dog came twice to do the walks in Ernstbrunn. For the first appointment, the dog had to do six different walks (two walks with each of the three walkers at two different sides). For the second meeting, the procedure was the same, so in the end each dog had twelve walks in total. Due to logistic straits, six dogs and their owners only made one appointment (six walks in total) (Table 4).

| DOGS | Street down <br> (Track1) | House (Track 2) | Walks in Total |
| :--- | :--- | :--- | :--- |
| Alika | 6 | 6 | $\mathbf{1 2}$ |
| Chloe | 6 | 6 | $\mathbf{1 2}$ |
| Dakota | 6 | 6 | $\mathbf{1 2}$ |
| Faye | 6 | 6 | $\mathbf{1 2}$ |


| Hancoc | 6 | 6 | 12 |
| :--- | :--- | :--- | :--- |
| Idefix | 6 | 6 | 12 |
| Luna | 6 | 6 | 12 |
| Mena | 6 | 6 | 12 |
| Merlin | 6 | 6 | 12 |
| Miley | 6 | 6 | 12 |
| Ultimo | 6 | 6 | 12 |
| Winnie | 6 | 3 | 12 |
| Becky | 3 | 3 | 6 |
| Forest | 3 | 3 | 6 |
| Luke | 3 | 3 | 6 |
| Nanuk | 3 | 3 | 6 |
| Shila | 3 | 3 | 6 |
| Tiffani | 3 |  |  |

Table 4: Number of walks for each dog: three walkers * two times the same path = six; three walkers * one time the same path $=$ three.

### 4.2.1 Standardized walk

Each track was 80 m long and was marked by four colour painted wooden poles. Two red poles marked the beginning and the end of the walk. In between there was one green and one blue stick. During the walk, the dogs had to do some requested commands. The dyad began to walk at one red stick, when they passed the green stick, they did the exercise "sit", then they went on till they reached the second red wooden stick which marked the end of the walk and then they dyad turned. When they passed the blue stick, the dogs should have done the exercise "down", and then they went on until they reached the first red wooden stick and then they repeated the whole procedure for a second time (Figure 1). Each of the participated walkers received an information sheet with the exact instructions for the procedure (Appendix A). The walkers were asked, not to speak to the camerawomen, not to act in a special way and walk as usual and not to aim at a "perfect" performance. There was no time limit and rewarding with dry food during the whole time of the walk was allowed ad libitum.


Fig. 1: Outline of the walk. The red colour poles marked the beginning of the walk, the end and where the dyad had to turn. At the green marking, the dog had to do the exercise "sit", at the blue marking it had to do the exercise "lie down". The distance between two markings was 20 cm , the whole distance between the two red markings was 80 cm .

All of the walks were done with the same long leash (ten meters), but the walkers were free to use the leash in any way they wanted.
The dyad was asked to do the exercises "sit" and "down". Basically all of the participating dogs were able to do both exercises. Walkers did verbal or hand commands to complete the exercises, some of them did both. The exercises were considered as successful, as soon as the dog sat down/lied down after the walkers command.

### 4.2.2 Recording the walk

Each walk was videotaped by me with a Sony handy cam, which was positioned in the middle of the route, two to four meters aside of the track. A dictaphone and a microphone were used by the walker, who had to carry these during the walks for recording the voices. For each walk, the following parameters were protocolled: date, time of the day, the number of the walk, the name of the walker and the name of the dog, which track was used, how the weather was during the walk, if anybody not involved in the study accompanied the walk and comments about special events, which might have happened.

### 4.2.3 Time period

The walks were done from January to June 2011. Because of the videotaping, walking was only possible in adequate daylight. To avoid disturbance as much as possible, the walks were scheduled at times when the game park was closed (during the winter season, the game park only opened on the weekends from 10 am to 4 pm ; during summer season the park was open every day, except Monday from 9 am to 5 pm ) or when there was a very low visitor frequency (early in the morning or on weekdays). One of the two tracks was in front of the WSC house, where no visitors were allowed. For this track, we made sure, that no dog or any other factors that might disturb the walk were present during walking.
To provide equal conditions for each subject and to avoid the dogs of getting bored walking always the same track, we varied walking at the two sides and we also varied the order of people walking with the dog. No walker walked two times with the dog in a row and we changed between the two sites as much as possible to avoid walking the same track two times in a row. Sometimes it happened, that two dogs were present on site at the same time (in these cases the owner of one dog was the friend of the other and vice versa). While one dog was walking the other dog was waiting some meters away, not visible for the walking dog.
The walkers, who were not in charge (for example when the owner was walking, the familiar person and the stranger had to wait), stood on one side of the street at the beginning of the walk (red marking). When we recognized, that the dog was distracted by the presence of the people, we asked them to keep some more distance, so that the walking dog was not able to see them any longer.

### 4.2.4 Additional requests for walkers

The walkers were all asked to fill in a NEO-FFI personality test for exploring walker's personality dimensions (McCrae \& Costa, 1987; 1989; Appendix B).
For a better understanding of the evolution and the complexity of human personality, Thurstonewas the first during the 1930ies to suggest 5 categories, in order to describe the personality of dog owners: "Neuroticism", "Extraversion",
"Openness", "Agreeableness" and "Conscientiousness". In 1999, a NEO-Five Factory Inventory (Neo-FFI) was produced by Costa and McCrae based on PCA on a number of attributes/features. This is a well established empirical approach, for exploring major and relevant human personality dimensions. Since then, this inventory is used by many research groups to study human personality of humans (Digman, 1996).

### 4.3 Observation

The software Adobe Premiere Pro CS5 was used for putting the video files together with the voice files. Behaviour coding was done with THE OBSERVER Video Pro® (Version 5.0; Noldus). For coding, we took the same configuration sheet, Margit Auer created for her study with the wolves (Auer, 2009), for the sake of comparability. The sheet included 10 behavioural classes (Appendix C). For testing the inter-observer reliability a second observer, not included in the study, coded six sample sequences of one minute each. The values of the two observers were compared and the showed over $87 \%$ agreements in duration (Cohen's Kappa: $87 \%$ ) and $90 \%$ in frequency (Cohen's Kappa: $90 \%$ )
All behaviour coding was conducted by one person (M. Heszle) and therefore an intra-observation was done on six sample sequences of one minute each, before (Cohen's Kappa: $89 \%$ in duration and $87 \%$ in frequency) and after coding all videos (Cohen's Kappa: $90 \%$ in duration and $92 \%$ in frequency).

### 4.4 Data preparation

In total we recorded 180 walks with 54 different dog-human dyads (Eighteen dogs * three different walkers). Each of the dogs did at least two different walks with each of the three different walkers, so we had 108 walks in different conditions. Six of the dogs just did one run, the other twelve dogs came twice to do a second run (the same conditions were set as we used for the first run). Six out of the 180 walks were incomplete. In five out of six walks, the walker broke off the walk because the dog did not want to move on. In one case there was a problem with the camera and only half of the walk was recorded. Only one dog (Nanuk; Table 1)
had two incomplete walks, the other four dogs had only one incomplete walk. For statistical analyses 174 complete walks were used. The data set was prepared with MS Excel 2003. For measuring the walk variables we took the total number of events happened and the total duration in percent.

### 4.5 Statistical analysis

We calculated a linear mixed effect model to investigate the influence of the walker, his/her personality traits, age and sex of the dog, sex of the walker, number of trial (first or second time of a walk), route, time of day, and weather, on the relative duration of a certain behaviour. The individual dog, its breed and the walker were involved in the model as random factor. Furthermore, the total frequencies of behaviours was analysed with a non-linear mixed effect model using a poisson distribution. In this model the influences of the walker, its personality traits, age and sex of the dog, sex of the walker, number of trial (first or second time of a walk), route, time of day, and weather were analysed, whereas the individual, its breed and the walker were involved in the model as random factor. Some behavioural traits, such as "dog pee", or "walker walk dog", did not occur frequently. Therefore, we were interested in finding factors that supports the incidence of such behavioural traits. Thus, we calculated a non-linear mixed effect model using a binomial distribution. We were using the same factors, described for the other models. To compare whether the personality traits of walkers differ between owner, stranger, and friend a Kruskal-Wallis test was calculated. The models were calculated with the program R 2.11.1 and the Kruskal-Wallis test with the program SPSS 18.0.

The 16 behavioural traits used for the statistical analysis were divided into two groups characterizing two important parameters for describing dyadic walk performance. The first group "cooperative behaviour" includes the use of the leash, the guidance behaviour and the calling behaviour of walkers. The second group describes the orientation towards the walking partner (Table 5).

| Cooperative Behaviour | Orientation behaviour |
| :--- | :--- |
| Strain at leash_initiated by the <br> walker | Walker orient towards the dog tactile |
| Strain at leash_initiated by the <br> dog | Walker not orientated towards the <br> dog |
| Leash loose | Dog orientated towards the walker |
| Guide conflict | Dog explore |
| Walker stand_initiated by the dog | Dog run/jump |
| Call come | Distance between the dyad_more <br> than 1 meter |
| Call name |  |
| Call sit |  |
| Call down |  |
| Excercise sit_not successful |  |

Table 5 shows the variables used for the analysis, divided into cooperative and orientation behaviour.

## 5 Results

### 5.1 The effect of the intensity of contact - differences between the three different walkers

### 5.1.1 Cooperative behaviour

We found an influence of the walker on the time the leash was strained during the walk (lme: $\mathrm{t}_{33}=5.981, \mathrm{p}=0.006$ ). The duration of walking with a strained leash was longer, when they walked with another person than the owner (Ime: t. ${ }^{33}=-2.673$, $\mathrm{p}=0.011$ ). There was no difference between the strange person and the friend (Ime: $\mathrm{t}_{33}=0.84, \mathrm{p}=0.40$ ) in that respect. Moreover the duration of walking with a loose leash was longer when dogs walked with owners than with friends or strangers (Ime: $\mathrm{t}_{34}=5.181, \mathrm{p}=<0,001$ ). Dogs initiated more often a strained leash, when they walked with a friend or with a strange person than with the owner ( n Ime: $\mathrm{t}_{28}=3.619, \mathrm{p}=0.001$ ). No such difference was found between the stranger and the friend ( nlme : $\mathrm{t}_{28}=0.28, \mathrm{p}=0.78$ ). The conflict over leadership lasted longer when the dog was with a stranger or a friend than with the owner (Fig. 2). "Sit" was more often successful when the owner issued the command, as compared to the stranger or the friend ( $n$ Ime: $\mathrm{t}_{30}=-2.10, \mathrm{p}=0.043$ ).


## Walker

Figure 2 shows the duration of a leadership conflict (total duration in \%) for all of the three walkers.
The duration of guide conflict for the owner differs significantly in comparison to the friend and the stranger (Ime: $\mathrm{t}_{33}=-2.526, \mathrm{p}=0.016$ ).

### 5.1.2 Orientation towards walking partner

Walkers differed in their tactile orientation (i.e. stroking or patting the dog during the walk) towards the dog (Ime: $\mathrm{t}_{33}=5.091, \mathrm{p}=0.012$ ). Actually, the friend was orientated towards the dog the most, then the owner came and the strange person was at least orientated towards the dog in a tactile way (Figure 3). Actually, walking partners were coded "orientated towards the other one", when the head was in the direction of the partner. Actually, the stranger was also not orientated towards the dog for a longer periods of time than the friend or the owner (Ime: $\mathrm{t}_{33}=3.474, \mathrm{p}=0.002$ ).


Figure 3 shows the orientation of walkers towards the dog (total duration in \%) for all the three walkers. The stranger spent least time orientated towards the dog (Ime: $t_{33}=-3.189, p=0.003$ ).

### 5.2 Effects of Owner Personality

We found no differences between the groups in any of the 5 NEO-FFI dimensions (Kruskal-wallis test: Neuroticism: Chi-Quadrat ${ }_{2}=0.08$, $\mathrm{p}=0.96$; Extraversion: ChiQuadrat $_{2}=1.84, \mathrm{p}=0.40$; Openness: Chi-Quadrat ${ }_{2}=0.23, \mathrm{p}=0.89$; Agreeableness: Chi-Quadrat $_{2}=2.46, \mathrm{p}=0.29$; Conscientiousness: Chi-Quadrat $_{2}=2.89, \mathrm{p}=0.24$ ).

### 5.2.1 Cooperative behaviour during the walk

Walkers high in extraversion (NEO-FFI dimension 2) and openness (NEO-FFI dimension 3) as well as walkers low in conscientiousness (NEO-FFI dimension 5) showed low frequencies of leadership conflicts (Figure 4). In the case of neuroticism (NEO-FFI dimension 1), we found no influence on the number of leadership conflicts. Dogs initiated less often a strained leash when they were with
walkers who scored high in extraversion (nlme: extraversion: $\mathrm{t}_{28}=-3.727, \mathrm{p}=<$ 0.001), high in conscientiousness or agreeableness (conscientiousness: $\mathrm{t}_{28}=-$ 2.104, $\mathrm{p}=0.045$; agreeableness: $\mathrm{t}_{28}=2.026, \mathrm{p}=0.052$ ) than when with persons low in these dimensions. In contrast dogs who walked with partners high in neuroticism initiated more often a strained leash (nlme: $\mathrm{t}_{28}=2.910, \mathrm{p}=0.007$ ) than with persons low in this dimension. Also the walkers who scored high in neuroticism themselves, initiated more often a strained leash (nlme: $\mathrm{t}_{31}=3.178$, $\mathrm{p}=0.003$ ) than individuals low in this dimension.

The exercise "sit" was more successfully executed by walkers high in extraversion, in conscientiousness, in agreeableness and in openness (nlme: extraversion: $\mathrm{t}_{30}=-$ 6.902, $\mathrm{p}=<0.001$; conscientiousness: $\mathrm{t}_{30}=-5.407, \mathrm{p}=<0.001$; agreeableness: $\mathrm{t}_{30}=2.165, \mathrm{p}=0.038$; openness: $\mathrm{t}_{30}=-2.618, \mathrm{p}=0.014$ ) than by individuals low in these dimensions. Walkers high in extraversion did less often call "sit" (nlme: $\mathrm{t}_{29}=4.198281, \mathrm{p}=<0.001$ ), "come" (nlme: $\mathrm{t}_{31}=-2.972, \mathrm{p}=0.006$ ) or the dog's name ( nlme : $\mathrm{t}_{35}=-2.468, \mathrm{p}=0.019$ ). In contrast, the higher people scored in neuroticism the more they called "come" during a walk (Figure 5). Walkers high in openness and in agreeableness did less often call "come" (nlme: openness: $\mathrm{t}_{31}=-3.290$, $\mathrm{p}=0.003$; agreeableness: $\mathrm{t}_{31}=-2.556, \mathrm{p}=0.016$ ) or "sit" (nlme: openness: $\mathrm{t}_{29}=3.063$, $p=0.005$; agreeableness: $t_{29}=2.768, p=0.010$ ).


Figure 4 shows the influence of personality on guide conflicts during a walk. a: shows that walkers high in extraversion showed less conflicts (nlme: $\mathrm{t}_{27}=-2.590$, $\mathrm{p}=0.016$ ); b : walkers high in openness showed also less conflicts (nlme: $\mathrm{t}_{27}=-2.367, \mathrm{p}=0.025$ ); c : walkers high in conscientiousness showed more often conflicts during a walk (nlme: $\mathrm{t}_{27}=-2.180 \mathrm{p}=0.038$ ).


Figure 5 shows the influence of a.): extraversion on the total number of calling "come". The higher the walker scored in extraversion the less often he called come (nlme: $t_{31}=-2.972, p=0.006$ ); b.): neuroticism on the total number of calling "come". The higher the walkers scored in neuroticism they more they called "come" (nlme: $\mathrm{t}_{31}=2.440, \mathrm{p}=0.021$ ).

### 5.2.2 Orientation towards walking partner

Walkers high in agreeableness and in conscientiousness were less often orientated towards the dog in a tactile way (lme: agreeableness: $\mathrm{t}_{24}=-4.235$, $\mathrm{p}=<0.001$; conscientiousness: $\mathrm{t}_{24}=5.165, \mathrm{p}=<0.001$ ), than persons low in these dimensions. Also, walkers high in neuroticism and in extraversion were more often touching the dog (Ime: neuroticism: $\mathrm{t}_{24}=2.986, \mathrm{p}=0.006$; extraversion: $\mathrm{t}_{24}=3.249$, $p=0.003$ ) than walkers low on these dimensions.

### 5.3 Effects of dog sex and owner gender

### 5.3.1 Cooperation behaviour and orientation towards the walking partner

### 5.3.1.1 Effects of dog sex

We found differences in the obedience of female and male dogs in response to the command "down" (nlme: $\mathrm{t}_{16}=-2.902, \mathrm{p}=0.010$ ): When walking with male dogs, walkers had to call less often "down" to succeed, than with female dogs. Moreover,
walkers initiated less often a strained leash when they walked with male dogs than with female dogs ( $n$ lme: $\mathrm{t}_{15}=-3.024, \mathrm{p}=0.009$ ). The time, the walker was not orientated towards the dog was shorter for male dogs than for female dogs (Ime: $\mathrm{t}_{15}=-2.311, \mathrm{p}=0.035$ ). There was also a difference in the duration of explorative behaviour between female and male dogs (Ime: $\mathrm{t}_{16}=9.799, \mathrm{p}=0.007$ ). Male dogs took significantly more time exploring during walks than female dogs did.

### 5.3.1.2 Effects of walker gender

Male walkers tend to call "sit" more often than female walkers (nlme: $\mathrm{t}_{29}=1.856$, $\mathrm{p}=0.073$ ). Also, male walkers tended to initiate more often a strained leash (nlme: $\mathrm{t}_{15}=-3.175, \mathrm{p}=0.006$ ) than female walkers did.
We did not find any effects of human gender on the orientation behaviour. We also did not find any interactions between owner's gender and the gender of dogs regarding cooperation behaviour or orientation behaviour.

### 5.4. Effects of food rewarding

We found no influence of the rate of food rewards on parameters characterizing cooperation (duration of a strained leash, number of initiating a strained leash, unsuccessful exercises, and guided conflicts). We also did not find any evidence, that dogs paid more attention towards the walker, when these had food in their hands.
But we found an influence on the duration of the walker's tactile orientation towards the dog (Ime: $\mathrm{t}_{117}=-2.657, \mathrm{p}=0.009$ ) and on the duration walkers were not orientated towards the dog (Ime: $\mathrm{t}_{119}=-1.970, \mathrm{p}=0.051$ ). The longer walkers had food in their hands, the shorter was the time, they touched the dog and the shorter was the duration of not being orientated towards the dog.

### 5.5 Effects of dog's age

We found that the older the dogs, the more often the walkers initiated a strained leash ( nlme : $\mathrm{t}=2.851, \mathrm{p}=0.0121$ ) and at the same time the more they called the dog's name (nlme: $\mathrm{t}_{16}=-2.735, \mathrm{p}=0.015$ ). And the older the dogs, the longer
walkers were not orientated towards the dog (Ime: $\mathrm{t}_{15}=2.617, \mathrm{p}=0.019$ ). Moreover, the older the dogs, the less often they were orientated towards the walkers (nlme: $t_{15}=17.459, p=0.001$ ) and the longer they kept a distance of over 1 metre to the walker (Ime: $\mathrm{t}_{16}=2.962, \mathrm{p}=0.009$ ).

### 5.6 Effects of second trial

We found no differences between the two trials with respect to the cooperative behaviour of the dyad. But we found a difference in the trials, with respect to the tactile orientation of the walkers towards the dogs. Walkers touched the dogs more in the second trial than in the first one (Ime: $\mathrm{t}_{117}=2.106, \mathrm{p}=0.037$ ). Furthermore, in the first trial, the dogs ran and jumped much more, than they did in the second one (Ime: $\mathrm{t}_{117}=5.344, \mathrm{p}=0.023$ ).

|  | Walker | Personality | Gender | $\begin{aligned} & \text { Food } \\ & \text { rewards } \end{aligned}$ | Age | Trial |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Strain at leash_initiated by the walker | 『 | $\checkmark$ | $\checkmark$ | x | $\checkmark$ | $\times$ |
| Strain at leash_initiated by the dog | $\square$ | $\checkmark$ | $\times$ | x | $\times$ | $x$ |
| Leash loose | $\checkmark$ | $\times$ | x | x | x | x |
| Guide conflict | $\checkmark$ | $\checkmark$ | X | X | $\times$ | $x$ |
| Walker stand_initiated by the dog | $\checkmark$ | $\times$ | $\times$ | X | X | x |
| Call come | $\times$ | $\checkmark$ | , | x | X | x |
| Call name | x | , | x | x | $\checkmark$ | x |
| Call sit | $\times$ | $\checkmark$ | $\times$ | $\times$ | $\times$ | x |
| Call down | X | $\times$ | $\checkmark$ | x | $\times$ | $x$ |
| Excercise sit_not successful | $\checkmark$ | $\checkmark$ | $\times$ | x | $\times$ | $x$ |
| Walker orient towards the dog tactile | $\checkmark$ | ¢ | X | $\times$ | $\times$ | $\checkmark$ |
| Walker not orientated towards the dog | $\square$ | $\times$ | ¢ | ¢ | ¢ | $x$ |
| Dog orientated towards the walker | $\times$ | X | $\times$ | $\checkmark$ | $\checkmark$ | x |
| Dog explore | X | $\times$ | $\checkmark$ | $\times$ | $\times$ | $\times$ |
| Dog run/jump | $\times$ | x | $\times$ | x | $\times$ | $\checkmark$ |
| Distance between the dyad_more than 1 meter | $\times$ | $\times$ | x | $\times$ | $\checkmark$ | $x$ |

Table 6 shows whether the behavioural trait was significant for a certain parameter: $p=<0.05$ or
not significant: $\mathrm{X}: \mathrm{p}=>0.05$.

## 6 DIscussion

The aim of this study was to investigate whether and to which extent the intensity of contact, the human-personality and the gender of the human and the animal affects cooperative performance in human-dog dyads. Although the interpretation of our results and the discussion should be done carefully, due to the relatively small sample size we had at our disposal for this study, we were able to build on previous studies and to contribute some interesting findings regarding the major parameters influencing human-dog relationships. In alignment with Auer (2009) our study showed, that familiarity benefits the cooperative behaviour of humans with their animals. In fact, the cooperation style of the dyads differed among the three groups of walkers, according to the amount of time they previously spent with the dogs and the social roles they play in their lives. Considering these results, we found a difference in the performance between the owners and the other walkers but interestingly there were no significant differences between friends and strangers. The findings by Topál et al. (1997) might support theses finding, showing that the more a dog is attached to a certain person, the more it is likely to behave like a member of a social group. Further it also confirms the statement that the development of complex human-animal relationships will depend on the nature and intensity of attachment (Bowlby, 1999). The friend of the dog used to be a good friend of the owner, who knew the dog well and saw it regularly (Table 2). We only found one case where the friend lived in the same household as the dog. To conclude these findings, it might be important for the dog, not only to know the person it walked with, but to be attached to it.

Concerning the orientation behaviour of walkers towards their dogs, strangers spent the shortest time touching the dog, whereas we did not find any difference between owners and friends. Furthermore strangers spent most of the time not looking at the dog, whereas owners and friends both paid more attention to the dog than the stranger. This suggests that the friends try to form some efficient relationship with the animal and therefore try to communicate with the dog and to pay attention to it. But to optimise
cooperative behaviour, this is not enough; in this direction it is important for the dog not only to be familiar with a person, but to be attached to her/him. Although strangers showed a less cooperative performance with the dog than owners, we did not find any indication of fear, avoidance or aggression of dogs towards strangers. This may indicate that dogs cooperate more readily with humans than wolves would do, even if they do not know them (comp. Auer, 2009). But further comparative testing is needed to confirm this idea. Human personality is an important factor influencing the nature of interaction between walkers and dogs. Its effect on dog-human relationship was already examined earlier (Kotrschal, 2009; Topál, 1997; Schöberl, 2009; Wedl, 2010). In fact, we found that the more neurotic an owner was the more tactile orientation he/she showed towards the dog and the more he/she tried to control the walk via a strained leash, this was also found by Aliabadi (2010). We also found that walkers high in extraversion and openness showed fewer leadership conflicts, than for example, walkers high in conscientiousness. The higher a walker scored in extraversion, in conscientiousness and in agreeableness, the less often the dog initiated a strained leash, but the other way for neuroticism. Also, walkers initiated more often a strained leash when high in neuroticism. Considering that dog-human dyads with people high in extraversion perform better in shared activities (Kotrschal et al., 2009), we may suggest that dogs in such dyads do not tend to take control over the walk by initiating a strained leash. These findings also coincide with the results by Margit Auer (2009) who also revealed that wolf walkers high in extraversion used the leash not as often as a tool for enforcement and they tended to guide less during a walk.

Neurotic owners have a close attachment to their dogs and therefore, they touch their dogs a lot (Auer, 2009; Aliabadi 2010). In our study also, people high in neuroticism touched their dogs more often than people low in this dimension, or people who scored high in agreeableness or in conscientiousness. Aliabadi (2010) found that owners high in neuroticism talked more in order to control the cooperative task. This we did not find, however, walkers high in neuroticism uttered "come" more often than walkers high in extraversion, openness or agreeableness did. This may support earlier findings that people high in neuroticism see their dogs as social
supporters rather than as buddies in shared activities (Kotrschal et al., 2009) and therefore, such walkers showed less control over their dog's despite their attempt to keep acoustic contact. Along these lines, walkers high in extraversion used the command "sit" sparingly and still were pretty more successful in making the dog comply. In contrast with Kotrschal et al. (2009) we did not find any interaction between gender of owners and dogs regarding cooperation behaviour or orientation behaviour. However, interpretation of our gender results suffers from small sample size and the fact, that we only had six male, but twelve female dogs and twenty-two female but only six male walkers in our study. In alignment with Aliabadi (2010), we found out that male owners exerted their control more by holding their dogs and therefore initiated a strained leash more often, than female walkers did. But in contrast to Aliabadi (2010) we found that walkers initiated a strained leash less often when walking with a male than a female dog. The command "sit" was uttered less often when walking with a male dog and the time, a walker was not orientated towards the dog was shorter for male dogs. Looking at these results, they might suggest, that male dogs cooperated more readily with the walker than female dogs did, but once again further studies with a bigger sample size would be necessary to prove these findings. Our results did not show any surprising outcomes concerning the influence of food rewards on a cooperative task. But we found an influence of food rewards on the duration of walkers touching the dog and on the duration walkers were not orientated towards the dog. The longer a walker had food in his hands, the shorter he was orientated towards the dog tactile and the shorter was the time period, he was not orientated towards the dog. This may suggest that walkers with food in their hands weren't able to touch the dog, but were focused on a good performance and therefore, tried to be more orientated towards the dog. However, we did not find any correlation between the rate of food reward and parameters characterizing the cooperative behaviour. Moreover, we did not find any hints that dogs paid more attention towards walkers who longer held food in their hands. Unlike in Margit Auer's study (2009), where she investigated the cooperative behaviour of human-wolf dyads, the walkers in the current study did not stringently need food for completing the walk and the exercises. The wolves from the Wolf Science

Centre in Ernstbrunn, used for the study of Margit Auer, are trained to cooperate with humans by being rewarded with food. Therefore the food reward is a more integrative part of their cooperative action (Auer, 2009).

Our results also revealed that the older a dog was, the more often the walker initiated a strained leash and the more often the walker called the dog's name and the less often they were orientated towards the walker. This suggests a decrease of cooperative behaviour in older dogs.

Twelve out of eighteen dogs were able to participate two times. As to the cooperative behaviour of the dog-human dyad, we found no differences between the two trials. But we did find that in the first trial, the dogs ran and jumped much more, than they did in the second one. This may not be surprising, due to the fact, that in the first trial, everything was new for them, but in the second trial they were already acquainted with the situation and therefore they were not interested anymore in running and exploring the area. But this is a clear indication that dogs in such walking projects show quick and distinct serial effects. Also the walker touched the dog more in the second trial, than in the first one. Hence both may have been more relaxed in the second walk, or the walker responded to the more relaxed behaviour of the dog. In any case, he/she was able to focus more on the dog during the second walk.

To conclude, our hypotheses and expectations on which this project was based were met. The cooperative interactions in a human-dog dyad indeed depend on the attachment and the intensity of contact between human and dog, on the personality of the owner and on human gender and dog sex. My findings may also provide the base for a better understanding of human-dog relationships and may help trainers to focus on a more systemic, i.e. dyadic approach in individual owner-dog training.

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## 8 APPENDICES

### 8.1 Appendix A: Handout for doing standardized walks

1) Please read through the Handout. If you have any queries, please ask me.
2) Conditions for a Walk: no rain- or snowfall (because of the camera); good daylight; motivated dogs
3) Each dyad has to do the walk three times. The same dyad is not allowed to do the walk two or three times in serial and if possible it should not walk more then once at the same day.
4) Performance
$\checkmark$ Try to walk uninfluenced, "as always"! Do not brace oneself or mind on perfectness because of the filming camera.
$\checkmark$ During the walk please do not contact with the cameraman/woman.
$\checkmark$ The order and place (look after coloured poles) of the practices have to be considered (s. course, layout and overview).
$\checkmark$ Do not do the practices with your back to the camera; The camera should see the faces of human and wolf - lateral presentation is optimal.
5) Also the spoken words are important for the analysis. Thus each wolfwalker gets a dictaphone and a small microphone with a short introduction about the handling. Afterwards we leash the wolves. From the enclosure to the beginning of the walk it takes about 10 minutes. I will antedate with the camera to be timely at my position. The red pole marks the beginning of the standardised walk. (Important: Switch on the recorder!). You walk until the green pole. There you do the first practice "sit". You walk on, pass the blue poles and turn at the red pole. Back at the blue pole you do the second practices "down" and walk on. Pass the green pole and turn at the red pole. Now you repeat this once again: do the practice three "sit" at the green pole, walk on, pass the blue and turn at the red pole. At the blue pole you do the
practice four "down" and walk on pass the green pole and when you pass the red pole the standardised walk is finished. One cycle needs about 7 to 10 minutes.
6) Anonymity

For the analysis each wolf-walker gets a number. Full anonymity can not be given during taking the data but for analysis and publication it is guaranteed.

## 7) Further

Additionally to the walks, each wolf-walker has to fill out a personality-test (NEO-FFI), a wolf-attitude questionnaire and a wolf-personality-scoring questionnaire.

### 8.2 Appendix B: NEO-FFI Personality Scoring

## Fragebogen

Name: $\qquad$ Ostum: $\qquad$

Alter $\qquad$

Beruf: $\qquad$

Schulabectus $\qquad$
 bung Iher cigenen Parsen eignen Wonnten. Lesen Sie bitte jede dieser auss-
 bh zutrifft coder nicht Zur Bewerturg jeder der ga Ausagen steht Ihren gine finffachatactute Skala cur verfigung. Krearen Se bitte an:

Sthrke Ablehumg wenn Sit der hussege aur keinen Fall custimiren oder fie flut wellig umeutrefferd haiten.


Ablehrang. acon Se der sulsige wher nicht zustimmen oder sie fur uncutreftend haltom, $\qquad$


Neutral, wenn de Aussage weder richtig noch falsch, also veder gutreffend hoot uncutrefend ist. $\qquad$


Zustimmung, wetm Sie der huscge cher Justimmen oder sie fur cutreffend halten $\qquad$

 oder sie fur wilig zutreffend halten. $\qquad$


Es gibe bei desem Fragebogen beine richtigen" oder "falschen" Antworten, und se misen bein Experte teime Expetton sem, um den Frapebegen angemesen bearworten cu bomen، Sie erfulen den Zuoll der Befragung ann besten, indem sie de Fragen go wahrheitegemble wie mbglich beantworten.
 webe am berten ausdrucht. Falls sie the Meinung mach dem dibeuten einmal andern sollten, strei-

 krenen Ste trotedem immer eine Antuort an, und awar de, weiche noth am ehesten auf Sie autrift Gegirntense bite jetat mit der betnlvorturgl


| 22. Peese beendruct mith wenif oder gar nicht |  |
| :---: | :---: |
| 24. Im Hinblek aut dis Abshthen areder bon th eher misch und skeptisch. | $9000$ |
| 25. Fh habe eine Reihe von klyen Zielen und arbete fystematich <br> 解號 24 |  |
| 26 Marmmot fuhle ith mith vellig vetlus. |  |
|  |  |
| 28, wh probice oft new umd fretrle Speisen aus. |  |
| 22. ©h glabe dacs mun wh den mebten Leuten ausgentat wird, wenn man es zulass. |  |
| 30. Ich vertridele eine Menge Zeit, bevor ich mit elnar Apbeit beglime. . . . . . . | - |
| 31. Ithempfinde selten Furcht oder Arget. |  |
| 32. Ith habe oft das Gefuhl wor Encrge Uberzuschamen. |  |
| 33. Ith thehme nur selten Notic won den trimmungen ader Cefuhten, die emahisdene Umpelamgen herwoflen | $3000$ |
| 34. Die meisten Mensthm, dioth mone, miden mich. | 000 |
| 35. Wh arbeite hart, um melne Zicle 74 umeldent |  |
| 3t. kh argere mich oft daruber whe ardect lette rich behundeln | $1000$ |
| 17. Wh bin ein frothlicr, gut gelaurter Mometh |  |
|  uncter religisen fultrititen achen sollten | $300$ |
| 30. Aanche Lute halten mich fur kalt und terechnend | $1000$ |
| 40. Wen th gine Verpllithtug eingehe, so larm man sith auf mich bestimmterlisen. | $000$ |
| 41. Zu haufig bin themtmutigt und wit autgoen, wemm ctws ghief gett... | $100$ |
| 42. Ich bin kein gut gelaumter Optimbt. |  |
| 43. Wenn ich Literatur lese oder en Cunswent betraght, mptinde ith mothmal iff Fobsteln eder eine Welle oter Eegeisterung. |  |

44. In Bezug auf meine Einstellangen bin th rubthern und utnachfiebig

45. Manchmal bin ich nicht wa verlashich oder xamerissig, wie fot sein salfe


4s kh bin selten trautig oder deprimiert

47. Wh fuhre ein hektothey Lebern
$\bigcirc 000 \bigcirc$
48. wh hate wenig I rierese, iter die Natur des Universoms oder die lage Aer Hensthert zu sperulkem.


49 sh we guche stetc ricteichtevoll und sencibed zu handein
 $\qquad$ BOOBC
51. th fuhle mich oft hilfles und wirwhe mir wine Person, die meine Problerme lest

52. Ith bin ein sehr abliver mensh. $\qquad$ ○○○○○
53. Ith bin sehr wistegierig G)OBC

F4. Henn ith Wenster mith mag, कo wipe ich imendes wuch offen 00000

56. Wanchmal war mer ctwan pornlich, dinit th nok am lichsten verstect hutte.

57. Lieber winde the meine eigenen thege gehen, als eine fruppe anzufituren. $\qquad$
58. ith habe oft Spar darkn, mit Theorien oder abstrakten ldeen au apelen.
 zu maripulieren.
60. Bei ailm, was the tue, strebe ith nach Perfeltion


|  | N | E | 0 | v | 4 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Summenerte |  |  |  |  |  |
| Zohl beantwarteter litems |  |  |  |  |  |
| Wittelwerte |  |  |  |  |  |
| Testwerte |  |  |  |  |  |

### 8.3 Appendix C: Configuration

Behavioral Class 1:
leash

| Behavior <br> Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| strain at leash | Is | walker or dog strains at the leash | State | initiator | direction |
| leash tight soft | It | walker keeps leash tight without pulling | State |  |  |
| leash loose | II | walker keeps leash loose and it droops | State |  |  |
| leash oos | Io | leash is out of sight | State |  |  |
| leash unspecifie | Iq | leash is not defined | State |  |  |

Behavioral Class 2:
phases

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| walk/no exercise | pw | the walk starts when walker and dog have passed the red mark and also end when both have passed the red mark; they do not do any exercise, or just have done an exercise (e.g. dog is sitting on command) | State |  |  |
| exercise sit | ps | do exercise sit; start when walker speak the command or show the hand signal (hand up); end when dog does the exercise successful (as soon as the dog is sitting) or when | State | exercise <br> success |  |


|  |  | walker break off |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| exercise down | pd | do exercise down; start when walker speak the command or show the hand signal (hand down); end when dog does the exercise successful (as soon as the dog lies) or when walker break off; sometimes the walker starts this exercise with the exercise "sit" | State | exercise success |  |
| exercise turn | pt | about-face at the red mark; start when walker initiate by turning, passing the red mark or calling the dog; end when both walk new direction | State |  |  |
| extra exercises | px | walker does some  <br> extra exercises  <br> during the walk; start   <br> and end see <br> exercise sit1   | State | $\begin{aligned} & \text { kind of } \\ & \text { exercise } \end{aligned}$ | exercise <br> success |
| call close | pc | walker call the dog close for doing the exercises sit1, sit2, down1 or down2. | State |  |  |
| meet stranger | pm | event occurs when walker or dog show the first reaction on strange park visitors (single or in a group), | Event |  |  |


|  |  | cars or other strange <br> things. |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| walk break off | pf | break off the walk | Event | brake off |  |
| phases oos | po | walker and dog are <br> out of sight | State |  |  |
| phas unspecified | pq | phases is not defined | State |  |  |

## Behavioral Class 3: postu/loc walker

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| stand still | CS | walker stands at one place and do not move, crouch, sit or lie; duration at least one second; inclusive scurry at the same spot | State | initiator |  |
| crouch/lie/sit | CC | walker crouches, knees get strongly bend up or walker reclines on surface | State |  |  |
| walk/go | cw | walker walks <br> forwards, <br> backwards <br> sidewards <br> inclusive pauses <br> between the steps <br> of maximum one <br> second | State | initiator |  |
| run | Cr | walker moves <br> faster than <br> walking; like <br> jogging  | State | initiator |  |
| loco walker oos | co | walker is out of sight, not visible | State |  |  |
| loco walker unsp | cq | posture or locomotion of the | State |  |  |


|  | walker is not <br> defined |  |
| :--- | :--- | :--- | :--- |

## Behavioral Class 4: posture/loc dog

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| stand | ms | dog stands at one place and do not sit, lie, explore or play; duration at least one second; inclusive scurry at the same spot | State | tail |  |
| sit | mi | dog is sitting down on the surface and does not explore or play - except during sitting on command | State | command |  |
| lie | ml | dog lie on the <br> surface, not <br> wallowing,  <br> exploring or <br> playing - except <br> during lie on <br> command  <br>   | State | command |  |
| walk | mw | dogwalks slowly forward, sideward or backward; inclusive pauses between the steps of maximum one second and does not explore or play | State | tail |  |
| run/trot/jump | mr | Dog move faster than walk and does not explore or play | State |  |  |



## Behavioral Class 5: orientati walker

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| or not to dog | on | the walkers head <br> is not orientated to <br> the dogs body | State |  |  |


| orient to dog | of | the walkers head <br> is orientated to the <br> dogs body | State | kind walker <br> orie |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| walker orien oos | oo | the walkers head <br> orientation is out of <br> sight | State |  |  |
| walker orie unsp | oq | orientation of the <br> walker is not <br> defined | State |  |  |

## Behavioral Class 6: orientation dog

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| or not to walker | rn | The dogs head is <br> not oriented to the <br> walkers body | State |  |  |
| orient to walker | rk | the dogs head is <br> oriented to the <br> walkers body | State |  |  |
| dog orient oos | ro | the dogs head <br> orientation is out of <br> sight | State |  |  |
| the dogs |  |  |  |  |  |
| dog orient unsp | rq | thentation is not <br> defined | State |  |  |

## Behavioral Class 7: vocalisation walker

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| call dogs name | va | walker calls the <br> dogs name | Event |  |  |
| call sit | vs | walker calls "sit" as <br> command | Event |  |  |
| call down | vd | walker"down" <br> "dows <br> command | Event |  |  |
| call come | vc | walker <br> "come" | Event |  |  |


| speak with dog | vf | walker speaks to dog; any kind of vokalisatoin (eg. whistle ...); with pauses in between not longer than one second | State |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| speak with person | vp | walker speaks to persons or to him/herselfe; any kind of vokalisation (eg. $r$ whistle...); with pauses in between $r$ long not longer than one second | State |  |  |
| do not speak | vn | walker dose not speak anything | State |  |  |
| do not hear | vh | the voice recording is too quiet too decide if the walker speaks or not | State |  |  |

## Behavioral Class 8

leadership

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| guide walker | gk | dog walk/run behind or lateral the walker or does the exercises the walker wants to do (even standing next to the walker without showing interest for going on) | State |  |  |


| guide dog route | gr | dog walks in front of the walker along the route | State |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| gui dog leave r | gf | dog walks in front of the walker and the walker follows and leave the route | State |  |  |
| guide conflict | gc | walker wants to go on along the route but the dog dose not come with him/her (waiting for the dog) or walker stops and dog wants to go on (calling the dog close) | State |  |  |
| guidance oos | go | dog and/or walker are/is out of sight so that it is not possible to decide guidance | State |  |  |
| guidance unspeci | gq | guidance is not defined | State |  |  |

## Behavioral Class 9:

## distance

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | distance between <br> walker and dog is <br> not more than one <br> meter; so that the <br> dog can easily be <br> touched by the <br> walker | State |  |  |
| less 1m | dl |  |  |  |  |
| between 1m 3m | db | distance between <br> walker and dog is | State |  |  |


|  |  | between one and three meters |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| more than 3 m | dm | distance between walker and dog is more than three meters; the walker is not possible to touch the dog | State |  |  |
| distance oos | do | dog and/or walker is out of sight and its not possible to decide the distance | State |  |  |

Behavioral Class 10:

## feeding

| Behavior Name | Code | Description | Type | Modifier 1 | Modifier 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | walker has some <br> dry food in his/her <br> hand or just grab <br> for some and the <br> hand is in the <br> pocket | State |  |  |$|$| fh |
| :--- |

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08/2003 culture festival Gmunden/OÖ

07/2002-09/2002 Animal Shelter; Steyr/Gleink

LANGUAGE SKILLS

|  | Understanding |  | Spoken Language |  | Writing |
| :--- | :---: | :---: | :---: | :---: | :---: |
|  | Hearing | Reading | Interaction | Production |  |
| English | C1 | C1 | B2 | B2 | B2 |
| Italian | B1 | B1 | A2 | A2 | A2 |
| French | A2 | B1 | A2 | A2 | A2 |

A2 Pre-Intermediate Level
B1 Intermediate Level
B2 Independent User
C1 Advanced Level

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European computer driving license (ECDL)

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SPRACHKENNTNISSE

|  | Verstehen |  |  |  | Sprechen |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Schreiben |  |  |  |  |
|  | Hören | Lesen | Interaktion | Produktion |  |  |
| Englisch | C1 | C1 | B2 | B2 | B2 |  |
| Italienisch | B1 | B1 | A2 | A2 | A2 |  |
| Französisch | A2 | B1 | A2 | A2 | A2 |  |
|  |  |  |  |  |  |  |

A2 Pre-Intermediate Level
B1 Intermediate Level
B2 Independent User
C1 Advanced Level

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Europäischer Computerführerschein (ECDL)

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